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Assessment on Stalking Proficiency of Mppt in Solar-Car Beneath Running Condition

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Abstract: Maximum Power Point Tracker (MPPT) is concentrated to get most extreme yield of PV whenever. There are many control techniques (e.g. Slope Climbing, Genetic Algorithm, Fibonacci Search Algorithm et al.) in MPPT. Nonetheless, the regular control technique isn't appropriate for moving vehicles' PV, for example, a solar car. In this manner, the creators tried an age normal for running state. In this examination, the effectiveness of Power Comparing Type and Hill Climbing Type MPPT frameworks is assessed by open air running analysis. In Addition, it isn't clarified about the itemized state for the age trademark on running time. In this way, we quantified intergradation of constant PV bend with a capacitor charge type I-V bend tracer. Accordingly, when the impact of shadow was extreme, it was discovered that plausibility of Power Comparing Method was helpful.

Keywords: MPPT, Solar-Car, DC to DC converter, PWM

I. INTRODUCTION

Research on photovoltaic (PV) frameworks has been done effectively from perspective of using normal vitality, and it is imagined that PV framework will be utilized for electric vehicle later on. There is the solar car as a trailblazer of the electric vehicle which utilizes the PV framework. In the running solar car, greatest power point voltage changes each time it runs. As one of the causes, Shadows of a tree and a telephone pole are distinguished as the reason. Moreover, there is a distinction in the episode point of the daylight by a bending body shape. In these cases, a P-V bend with some pinnacle focuses happens.

Hence, MPPT and the age control circuit for working point standardization are utilized. There are plural control strategies in MPPT. Be that as it may, the appropriate controlling strategy for versatile articles, for example, the solar car, has couple of instances of study. Along these lines, the creators analysed the legitimacy of MPPT which utilized the power looking at technique (PCM) and slope climbing strategy (HCM). The block diagram of MPPT is in Fig. 1.



Fig. 1. Block diagram of MPPT





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II. MPPT FUNCTIONAL DESCRIPTION

2.1 Constructed MPPT

This MPPT was intended for the solar car of 480W class. Initially three arrangements of MPPT(s) are mounted in a sun based vehicle. One of the sets was utilized in the trial. The A/D converter and The PWM yield work are required for control of MPPT. PIC16F88 has those capacities without anyone else's input. Thusly, PIC16F88 was utilized for control of MPPT. Voltage transformation was performed utilizing the non-confined PWM venture down converter. Specification of MPPT is mentioned in Table 1.

Table 1 Specification for MPPT	
Input Voltage	
	12V~100V
(open circuit voltage)	
Battery Voltage	
	9.6V~80V
(load voltage)	
Output Current	3A(MAX)
Max Power	160W

2.2 Control Algorithm

The stream outline of the PCM and the HCM is studied in this control algorithm. The component of every calculation is as per the following. PCM measures the PV's yield from the open circuit voltage to the short - circuit current of PV on the double. After the yield of PV is estimated, PV is worked at the greatest power point voltage. By this strategy, albeit greatest power point voltage can be found positively, estimation takes longer time than that of the HCM. Along these lines, a power age misfortune emerges by estimation a bit. First in HCM, MPPT measures the yield control close to the working voltage of the present PV. Next, when the deliberate electric power is bigger than the present working voltage, it is worked at new working voltage. At the point when the yield control is the equivalent or littler, PV is worked at the present working voltage. Since the structure of HCM is straightforward, it is feasible additionally in a simple circuit. Nonetheless, HCM may slip by into halfway arrangement (voltage isn't the genuine biggest power point). In a PV framework set on a portable article like a solar car, most extreme power point voltage is changed quickly for subseconds. In this way, it is important to make estimation procedure of electric power fast.

2.3 Capacitor Charger Type

In this investigation, The P-V bend when the solar car is running must be estimated ceaselessly so as to assess activity of MPPT. The P-V bend changes the frame sequentially. In this manner, estimation time and an estimation interim should have been abbreviated however much as could be expected. Be that as it may, the estimation device which can fill the interest was not ready to be gotten in this examination. At that point, the capacitor charge type I-V bend tracer was developed. The capacitor charge type I-V bend tracer gains the P-V bend by estimating the transient PC.

III. TEST OF I-V CURVE TRACER

The built I - V Curve tracer was contrasted and the capacitor charge type I-V bend tracer of instant article (EIKO INSTRUMENTS Co., Ltd. MP-140). The test was directed inside. The monocrystalline PV of one sheet was associated with I-V bend tracer. The light source utilized the incandescent light. A test outcome is looked. Result which I-V bend tracer estimated concurred with MP-140.

IV. TEST METHOD

It was tested around 13:15-14:10 on October 22th, 2007. Little solar car KAIT-AMATERAS of 480W was utilized for examination vehicle. There is a sorry excuse for trees in the south straight line of an investigation course. In this examination, it ran a 400m course in counter clockwise at a normal speed of 20km/h. The monocrystalline PV (Table 2) modules have 12 sheets. Besides, sidestep diode is associated with every module. The aggregate greatest yield of 12 sheets is 480W. Two frameworks were set up in this trial has been examined. Every framework was comprised of arrangement associated four PV modules. The aggregate most extreme yield of every framework is 160W. MPPT was

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associated with one framework and the I-V bend tracer was associated with another framework. I-V bend tracer was utilized so as to gauge the genuine most extreme power utilized as criteria. We expelled the shelter, so as to stifle the distinction of the created yield of two frameworks.

	*
Model No.	FT132-E
PV type	Monocrystalline silicon
Power(Max)	39.8W
Maximum Power Voltage	15.8V
Maximum Power Current	2.52A
Open Circuit Voltage	19.4V
Short Circuit Current	2.70A
Conversion Efficiency	13.4%
Panel Outer Size	W690×L430×H1.5mm

Table 2 Rating of PV

This control calculation is following the P-V bend from the open circuit voltage to the short out current of PV. Be that as it may, the working voltage of PV did not turn out to be under 40V. This is the impact of the voltage of the heap associated with MPPT. From this thing, when a MPPT of venture down sort is utilized and most extreme power point voltage is lower than the heap voltage, it is demonstrated that it can't find greatest power point. This arrangement needs to utilize a protected kind converter.

The circumstance of the P-V bend of a portable item, for example, a sun oriented vehicle is only here and there appeared. At that point, the P-V bend which the built I-V bend tracer estimated is also studied. These P - V bends are shown at interims of 500ms on the double. Irradiance as of now is precarious. Along these lines, the running P-V bend is changing the shape in moment. From this thing, if the interim which estimates a P-V bend is excessively long, it will be normal that it ends up hard to become more acquainted with the correct yield of PV.

4.2.1 POWER COMPARING METHOD

In the first place, the power age attributes in The PCM are derived using MPPT algorithm. Amid a test, since mists turned out for some time, sun based radiation isn't steady. Accordingly, the yield of PV is not really steady. The fall of the yield of PV by the shade of a tree on an exploratory course is close for around 40 seconds and around 120 seconds. The incorporated aggregate of the genuine most extreme power point which the I-V bend tracer estimated was 3.4Wh. Nonetheless, the info electric vitality to MPPT was 3.58Wh. It is suspected that the reason for this electric power distinction is the impact

4.2.2 HILL CLIMBING METHOD

The normal for HCM is seemed in various investigations. Irradiance was steady at the season of the examination of the HCM. The incorporated aggregate of the genuine greatest control point which the I-V bend tracer estimated was 4.36Wh. The information electric vitality to MPPT was 4.87Wh. The control highlight of HCM has showed up in where the creation of power diminished. The reason is wooden shade. Contrasted and PCM, activity of HCM has inert movement until the point when it moves to new greatest power point voltage.

V. CONDITIONAL METHODS

5.1 COMPARATIVE APPROACH

For the most part, the yield of the PV modules is relative to a measure of irradiance. At that point, increment decline rate of irradiance is determined. Next, increment decline rate of the info intensity of MPPT and genuine most extreme power is subtracted.

5.2 SHADOWLESS CONDITION

The working trademark under the steady irradiance and without shadow is looked. The Dissipating information of Xpivot demonstrates the variety of irradiance. At the point when a most extreme power point is gotten, the estimation of

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the Y - pivot approaches 0. The standard deviation of every strategy was 4.5 in PCM and 0.3 in HCM. Contrasted and PCM, it is felt that HCM is pursued pinnacle control better. In any case, irradiance variety was broad at the season of the PCM's analysis. Additionally, it is believed that the log timing of estimating instrument and the testing timing of PCM have covered. In this way, it can't pronounce yet that the accompanying ability of HCM is superior to PCM.

5.3 SHADOW CONDITION

Demonstrating a working trademark with a shadow and its standard deviation is 9.1 in HCM and 7.2 in PCM. Thus, it is viewed as that following capacity of the PCM is better. It should make reference to particularly - in spite of the fact that there is an estimation blunder of PCM, it is that the standard deviation of PCM is lower than HCM. That is, the point at which the impact by a shadow builds, it turns into that the accompanying ability of PCM is better than HCM.

CONCLUSION

The working normal for MPPT utilizing the PCM and the HCM was estimated and talked about. Therefore, when the impact of a shadow was extraordinary, the likelihood that PCM was helpful was proposed. Be that as it may, the distinction of the PV yield by each controlling strategy is as yet obscure. Likewise for the reason, the estimating state of PV yield needs more deliberate.

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BIOGRAPHY



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