

ANALYSIS AND EFFECT OF GENERALIZED UNIFIED POWER FLOW CONTROLLER: AN OPTIMAL LOCATION STRATEGY

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Abstract: The present technological developments in power electronics industry increase the utilization of various types of Flexible AC Transmission Systems (FACTS) controllers. Depending on the type of converters connection, there are single and multi-line FACTS controllers. Based on the type of connection, amount of the compensation and the advantage of convertible static compensators (CSC), Generalized Unified Power Flow Controller (GUPFC) is presented in this paper. Voltage source based power injection model of GUPFC is used to incorporate this device in Newton Raphson load flow solution, to analyze the effect of this device on system parameters. The proposed methodology is tested on standard IEEE-5 bus and IEEE-14 bus test systems with supporting numerical and graphical results.

Keywords: Generalized Unified Power Flow Controller; Optimal location; Voltage source based model; Incorporation procedure

I. INTRODUCTION

The basic concept of these FACTS controllers, because of incorporating self commutated semiconductor devices, the power flow can be diverted through some of the specific transmission lines, so as to increase the power transfer capability of the lines to its maximum limits such as thermal as well as voltage stability and security limits to minimize the impact on the environmental conditions. Using these devices, it is possible to control the voltage angle and magnitude at the system buses and the power flow through the transmission lines by varying the transmission line impedance of transmission system.

Based on the type of connection of the converters in a system, these FACTS controllers can be classified as series, shunt, combined series-shunt and combined series-series controllers. Similarly, based on the controlling purposes, these are classified as single line power flow controllers and multi-line power flow controllers. The latest convertible static compensators such as interline power flow controllers, generalized unified power flow controllers, etc., are developed to control multiple transmission lines simultaneously.

The Unified Power Flow Controller (UPFC) can be used for simultaneous control of the power system parameters (voltage, impedance, phase angle), or any of the above combinations [1, 2] as it is a versatile and effective device. This device consist one series converter coordinated with one shunt converter. An optimal location to install UPFC based on real power flow performance index is given in [3-5]. A steady state model of UPFC in terms of power injections is discussed in [6]. UPFC is a versatile device can control the active power and reactive power independently or simultaneously. Similarly, the voltage magnitude at system buses can also be controlled. A comprehensive load flow model for UPFC, to incorporate into existing Newton-Raphson (NR) Load flow is

presented in [7]. An algorithm is proposed for determining the optimum flow and size of UPFC for power flow applications [8]. A set of analytical equations are derived to control any combination of the power system parameters or none of them [9]. It is possible to study the power flow control in the presence of UPFC by obtaining sensitivity matrix of the power system [10]. The UPFC operation, control, sequencing, and protection methodologies under practical constraints are discussed in [11]. The congestion management in power system is possible with the selection of suitable location and settings of its control parameters [12]. An effective injection modeling approaches to power flow analysis in the presence of UPFC is discussed in [13-15]. Power Injection Model (PIM) of UPFC and its effect, based on location are analyzed in [16, 17]. Advanced UPFC model to reuse NR Load flow has been developed in [18].

The complete working procedure and fundamental frequency model of GUPFC is described in [19]. A fuzzy rule based model for GUPFC is proposed in [20]. In [21], a mathematical model of the GUPFC suitable for power flow is proposed. Nonlinear predictor-corrector primal-dual interior-point optimal power flow algorithm for GUPFC is presented in [22]. Voltage source based mathematical models of the GUPFC and its implementation in Newton power flow is presented in [23]. The design of the GUPFC damping controller is designed in [24]. Analysis of sub synchronous resonance with GUPFC is presented in [25].

From the careful review of the literature, it is identified that, voltage source converter based modelling is easy to model the FACTS controllers to analyse the effect of these controllers on a given system. In this paper, one of the multi-line convertible static compensator popularly known as Generalized Unified Power Flow Controller (GUPFC)

is modelled using voltage source converter based modelling. The complete incorporation procedure in conventional NR load flow algorithm is also presented. To maximize the effectiveness and obtained maximum benefit out of this device, it should be installed in an optimal location. In this paper, an optimal location of GUPFC is identified through contingency analysis. The effectiveness of the proposed methodology with GUPFC in an optimal location is studied on standard IEEE-5 bus and IEEE-14 bus test systems with supporting graphical and numerical results.

II. MATHEMATICAL MODELLING OF GUPFC

In general, GUPFC consist three voltage source converters and using this basic configuration, it can control power flow in two transmission lines simultaneously by varying device control parameters. For the sake of explanation, the complete voltage source based mathematical modeling of GUPFC is presented in this section. The principle configuration of GUPFC connected between buses i, j and k is shown in Fig.1.

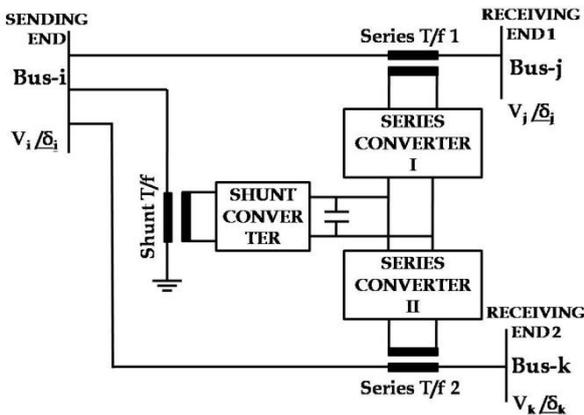


Fig 1. Schematic diagram of GUPFC

In this configuration, two voltage source converters are connected in two different transmission lines having a common bus. The third converter is connected at this common bus and acts as a shunt connected voltage source converter. This shunt converter supplies the power that is supplied by the series converters. All these converters are connected through a common DC link to exchange the power flow.

For the sake of simplification, it is assumed that, the voltage injected by the series converters is sinusoidal and the reactance of the coupling transformer is neglected. With these assumptions, the final voltage source model of GUPFC is shown in Fig.2. The voltages at GUPFC connected buses can be expressed as

$$\bar{V}_m = |V_m| \angle \delta_m \quad \forall \quad m = i, j, k \quad (1)$$

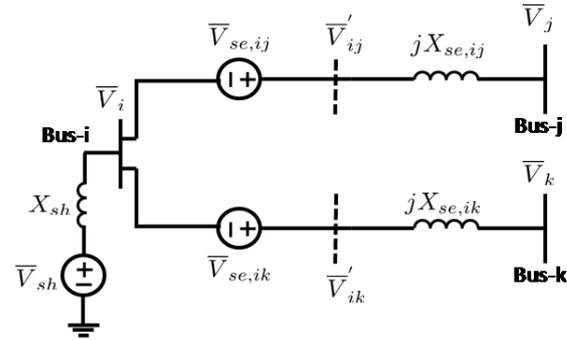


Fig.2. Voltage source model of GUPFC

The voltage injected by the series converters can be expressed as

$$\bar{V}_{se,im} = |V_{se,im}| \angle \delta_{se,im} \quad \forall \quad m = j, k \quad (2)$$

In Fig.2, the voltage behind the series voltage source can be expressed for both converters as

$$\bar{V}'_{im} = \bar{V}_i + \bar{V}_{se,im} \quad \forall \quad m = j, k \quad (3)$$

To develop the power injection model, the voltage source model is converted into an equivalent current source model using Norton's theorem and is shown in Fig.3.

$$\bar{I}_{se,im} = -jB_{se,im} \bar{V}_{se,im} \quad (4)$$

Where, $B_{se,im} = \frac{1}{jX_{se,im}}$ is the admittance of the coupling transformer.

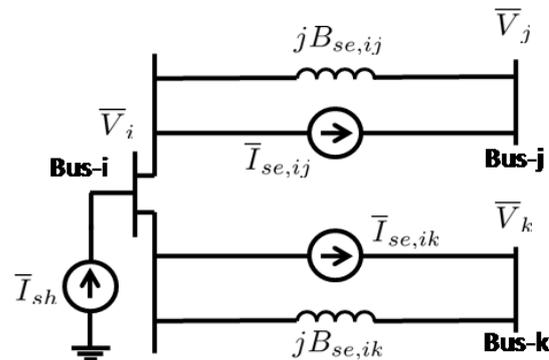


Fig.3. Equivalent current source model GUPFC

Using this, the power injected by these sources at the device connected buses can be expressed as

$$\bar{S}_{i,se} = \bar{V}_i (-\bar{I}_{se,ij} - \bar{I}_{se,ik})^* \quad (5)$$

$$\bar{S}_{m,se} = \bar{V}_m \bar{I}_{se,im}^* \quad (6)$$

$$\text{Using Eqns. (4), (5) and (6) can be simplified as}$$

$$\bar{S}_{i,se} = \sum_{m=j,k} (-jV_i V_{se,im} B_{se,im} \angle (\delta_i - \theta_{se,im})) \quad (7)$$

$$\bar{S}_{m,se} = jV_m V_{se,im} B_{se,im} \angle (\delta_m - \theta_{se,im}) \quad \forall \quad m = j, k \quad (8)$$

The final series voltage source with the respective power injections is shown in Fig.4.

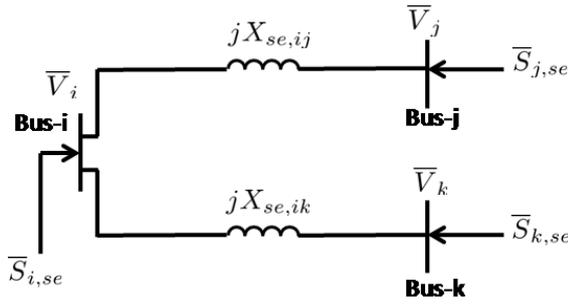


Fig.4. Equivalent series voltage source model of GUPFC

Similarly, the shunt connected voltage source converter can be modeled as an equivalent power injection at the respective bus. In this modeling, it is assumed that, the reactive power injected by the shunt converter is zero, because the purpose of this reactive power is to maintain the voltage magnitude at the converter connected bus. The equivalent shunt voltage source model of GUPFC is shown in Fig.5. The net active power injected at shunt converter connected bus can be expressed as

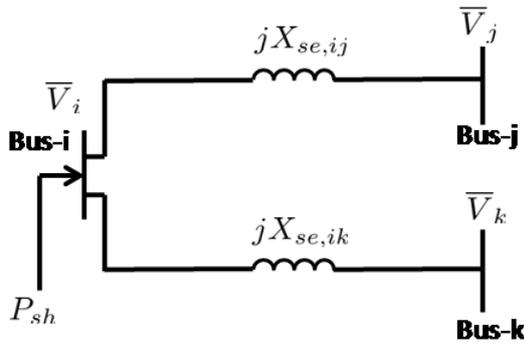
$$P_{sh} = -P_{series,ij} - P_{series,ik} \quad (9)$$


Fig.5. Equivalent shunt voltage source model

The amount of apparent power supplied the series converters can be calculated as

$$\bar{S}_{series,im} = \bar{V}_{se,im} \bar{I}_{ij}^* = j \bar{V}_{se,im} B_{se,im} (\bar{V}_{ij}' - \bar{V}_m)^* \quad \forall m = i, j, k \quad (10)$$

Using Eqn (3), after simplifying, the expressions for active and reactive powers supplied by the series converters derived are

$$P_{series,im} = V_i V_{se,im} B_{se,im} \sin(\theta_{se,im} - \delta_i) - V_m V_{se,im} B_{se,im} \sin(\theta_{se,im} - \delta_j) \quad \forall m = j, k$$

$$Q_{series,im} = -V_i V_{se,im} B_{se,im} \cos(\theta_{se,im} - \delta_i) + V_m V_{se,im} B_{se,im} \cos(\theta_{se,im} - \delta_j) - V_{se,ij}^2 B_{se,ij} \quad \forall m = j, k$$

The final power injection model is obtained by combining series voltage source model and shunt voltage source model. The combined model is shown in Fig.6. The respective power injections at GUPFC connected buses can be obtained as

$$P_i^{gupfc} = 2V_i V_{se,ij} B_{se,ij} \sin(\delta_i - \theta_{se,ij}) + 2V_i V_{se,ik} B_{se,ik} \sin(\delta_i - \theta_{se,ik}) - V_j V_{se,ij} B_{se,ij} \sin(\delta_j - \theta_{se,ij}) - V_k V_{se,ik} B_{se,ik} \sin(\delta_k - \theta_{se,ik})$$

$$Q_i^{gupfc} = -V_i V_{se,ij} B_{se,ij} \cos(\delta_i - \theta_{se,ij}) - V_i V_{se,ik} B_{se,ik} \cos(\delta_i - \theta_{se,ik})$$

$$P_j^{gupfc} = -V_j V_{se,ij} B_{se,ij} \sin(\delta_j - \theta_{se,ij})$$

$$Q_j^{gupfc} = V_j V_{se,ij} B_{se,ij} \cos(\delta_j - \theta_{se,ij})$$

$$P_k^{gupfc} = -V_k V_{se,ik} B_{se,ik} \sin(\delta_k - \theta_{se,ik})$$

$$Q_k^{gupfc} = V_k V_{se,ik} B_{se,ik} \cos(\delta_k - \theta_{se,ik})$$

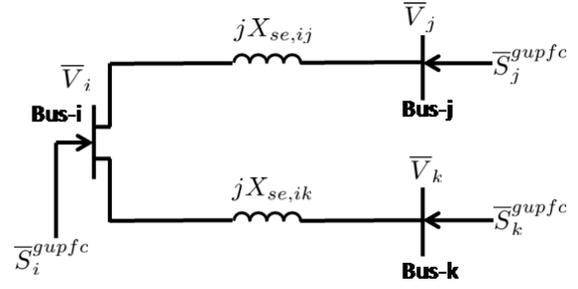


Fig.6. Equivalent power injection model of GUPFC

III. INCORPORATION OF GUPFC MODEL IN NEWTON RAPHSON ALGORITHM

To incorporate GUPFC in a given network, the conventional system equation in Newton Raphson load solution should modify to show the impact of the device. The developed power injection model is very to incorporate in a given power system by modifying the Jacobian and power mismatch equations at the IPFC connected buses. The final steady state network equation in the presence of this device can be expressed as

$$\begin{pmatrix} \Delta P \\ \Delta Q \end{pmatrix} + \begin{pmatrix} P^{gupfc} \\ Q^{gupfc} \end{pmatrix} = \left(\begin{pmatrix} H & N \\ J & L \end{pmatrix} + \begin{pmatrix} H^{gupfc} & N^{gupfc} \\ J^{gupfc} & L^{gupfc} \end{pmatrix} \right) \begin{pmatrix} \Delta \delta \\ \Delta V \end{pmatrix}$$

Where, ΔP , ΔQ are the respective power mismatch vectors, $\Delta \delta$, ΔV are the vector increments with respect to voltage magnitude and angles, H , N , J , and, L are the partial derivatives with respect to δ and V respectively.

The respective power mismatch equations and Jacobian elements corresponds to GUPFC connected buses can be represented as

A. Modifications in power mismatch equations

The power mismatch equations at the GUPFC connected buses can be modified by adding the GUPFC injected powers to the power mismatch equations without device. These power mismatch equations can be expressed as

$$\Delta P_m^{gupfc} = \Delta P_m^0 + P_m^{gupfc} \quad \forall m = i, j, k$$

$$\Delta Q_m^{gupfc} = \Delta Q_m^0 + Q_m^{gupfc} \quad \forall m = i, j, k$$

B. Modifications in Jacobian elements

The diagonal and off-diagonal elements of H^{gupfc} , are

$$H_{ii}^{gupfc} = \frac{\partial P_i^{gupfc}}{\partial \delta_i} = -Q_j^{gupfc} - Q_k^{gupfc}$$

$$H_{jj}^{gupfc} = \frac{\partial P_j^{gupfc}}{\partial \delta_j} = -Q_j^{gupfc}$$

$$H_{kk}^{gupfc} = \frac{\partial P_k^{gupfc}}{\partial \delta_k} = -Q_k^{gupfc}$$

$$H_{ij}^{gupfc} = \frac{\partial P_i^{gupfc}}{\partial \delta_j} = Q_j^{gupfc}$$

$$H_{ji}^{gupfc} = \frac{\partial P_j^{gupfc}}{\partial \delta_i} = Q_j^{gupfc}$$

$$H_{ik}^{gupfc} = \frac{\partial P_i^{gupfc}}{\partial \delta_k} = Q_k^{gupfc}$$

$$H_{ki}^{gupfc} = \frac{\partial P_k^{gupfc}}{\partial \delta_i} = Q_k^{gupfc}$$

Similarly, the diagonal and off-diagonal elements of N^{gupfc} , are

$$\begin{aligned}
 N_{ii}^{gupfc} &= |V_i| \frac{\partial P_i^{gupfc}}{\partial V_i} = -P_j^{gupfc} - P_k^{gupfc} \\
 N_{jj}^{gupfc} &= |V_j| \frac{\partial P_j^{gupfc}}{\partial V_j} = P_j^{gupfc} \\
 N_{kk}^{gupfc} &= |V_k| \frac{\partial P_k^{gupfc}}{\partial V_k} = P_k^{gupfc} \\
 N_{ij}^{gupfc} &= |V_j| \frac{\partial P_i^{gupfc}}{\partial V_j} = -P_j^{gupfc} \\
 N_{ji}^{gupfc} &= |V_i| \frac{\partial P_j^{gupfc}}{\partial V_i} = P_j^{gupfc} \\
 N_{ik}^{gupfc} &= |V_k| \frac{\partial P_i^{gupfc}}{\partial V_k} = -P_k^{gupfc} \\
 N_{ki}^{gupfc} &= |V_i| \frac{\partial P_k^{gupfc}}{\partial V_i} = P_k^{gupfc}
 \end{aligned}$$

The diagonal and off-diagonal elements of J^{gupfc} , are

$$\begin{aligned}
 J_{ii}^{gupfc} &= \frac{\partial Q_i^{gupfc}}{\partial \delta_i} = 0 \\
 J_{jj}^{gupfc} &= \frac{\partial Q_j^{gupfc}}{\partial \delta_j} = P_j^{gupfc} \\
 J_{kk}^{gupfc} &= \frac{\partial Q_k^{gupfc}}{\partial \delta_k} = P_k^{gupfc} \\
 J_{ij}^{gupfc} &= \frac{\partial Q_i^{gupfc}}{\partial \delta_j} = 0 \\
 J_{ji}^{gupfc} &= \frac{\partial Q_j^{gupfc}}{\partial \delta_i} = -P_j^{gupfc} \\
 J_{ik}^{gupfc} &= \frac{\partial Q_i^{gupfc}}{\partial \delta_k} = 0 \\
 J_{ki}^{gupfc} &= \frac{\partial Q_k^{gupfc}}{\partial \delta_i} = -P_k^{gupfc}
 \end{aligned}$$

Similarly, the diagonal and off-diagonal elements of L^{gupfc} , are

$$\begin{aligned}
 L_{ii}^{gupfc} &= |V_i| \frac{\partial Q_i^{gupfc}}{\partial V_i} = 2Q_i^{gupfc} \\
 L_{jj}^{gupfc} &= |V_j| \frac{\partial Q_j^{gupfc}}{\partial V_j} = Q_j^{gupfc} \\
 L_{kk}^{gupfc} &= |V_k| \frac{\partial Q_k^{gupfc}}{\partial V_k} = Q_k^{gupfc} \\
 L_{ij}^{gupfc} &= |V_j| \frac{\partial Q_i^{gupfc}}{\partial V_j} = 0 \\
 L_{ji}^{gupfc} &= |V_i| \frac{\partial Q_j^{gupfc}}{\partial V_i} = Q_j^{gupfc} \\
 L_{ik}^{gupfc} &= |V_k| \frac{\partial Q_i^{gupfc}}{\partial V_k} = 0 \\
 L_{ki}^{gupfc} &= |V_i| \frac{\partial Q_k^{gupfc}}{\partial V_i} = Q_k^{gupfc}
 \end{aligned}$$

IV. OPTIMAL LOCATION STRATEGY

From the careful review of the literature, it is identified that, FACTS controllers should be installed in an optimal location to maximize the effectiveness of the same. In this paper, an optimal location to install GUPFC is identified using contingency analysis. The conventional contingency analysis process through performance and severity indexes is used. In general, contingency analysis is a process of removing one of the transmission lines from a given network and identifying the total number of overloaded lines and their loadings. Using this, the performance index is calculated using

$$\text{Performance index } (PI_i) = \frac{S_i}{S_i^{max}}$$

Where, S_i is the current apparent power flow through ith line, S_i^{max} is the maximum MVA limit of ith line.

After calculating performance indexes of the over loaded lines under a contingency, severity index for each of the contingencies can be calculated using

$$\text{Severity index} = \sum_{i=1}^{NL} (PI_i)^{2m}$$

Where, NL is the total number of over loaded lines, m is a constant considered to be 1 (one).

Based on the severity index values, rankings are assigned to each of the contingency. Finally, the power flows under rank-1 contingency are obtained. As GUPFC require two different transmission lines with a common bus. Hence, from the line flows information under rank-1 contingency, the lines which has highest power flow margin are identified to install GUPFC. To reduce the computational burden the following heuristic rules are formulated to identify an optimal location of this device.

1. GUPFC should be installed between two PQ buses only provided no shunt compensators are connected.
2. The tap changing transformer connected lines are not considered to install GUPFC.

V. RESULTS AND ANALYSIS

In this section, the proposed voltage source based power injection model of GUPFC is incorporated in a given power system using the procedure given in section-3 and the proposed methodology is tested on standard 5 bus and 14 bus test systems.

A. Example-1

IEEE-5 bus system with five buses and seven transmission lines is considered. Initially, contingency analysis is performed on this system and the obtained results are tabulated in Table.1. In this table, overloaded lines and their respective performance indexes for each of the contingency line are tabulated. The respective severity index values under each of the contingency are tabulated in Table.2. From this table, it is identified that, line connected between buses, 2 and 5 is the most critical one as it has highest severity index value when compared to other contingencies. The line flows under this critical contingency are tabulated in Table.3. From this table and the heuristic rules formulated in section.4, the optimal location to install GUPFC is identified between buses 4, 2 and 3 i.e. in lines 4 and 6. The further analysis is assumed that, IPFC is connected in this location.

TABLE.1. RESULT OF CONTINGENCY ANALYSIS OF IEEE-5 BUS SYSTEM

S. No.	Outage line	Over loaded lines	Line flow (MVA)	Line limit (MVA)	PI
1	1-2	1-3	106.011	100	1.0601
		3-4	112.4979	100	1.125
2	1-3	1-2	110.6946	100	1.1069
3	2-3	-	-	-	-
4	2-4	3-4	100.4305	100	1.0043
		3-4	152.5254	100	1.5253
5	2-5	4-5	147.2209	100	1.4722
		1-2	110.5707	100	1.1057
7	4-5	-	-	-	-

TABLE.2. SEVERITY INDEX VALUES OF IEEE-5 BUS SYSTEM

S.No.	Outage line	Severity Index	Rank
1	1-2	2.389411	2
2	1-3	1.225329	3
3	2-3	-	7
4	2-4	1.008628	5
5	2-5	4.493799	1
6	3-4	1.222587	4
7	4-5	-	6

TABLE.3. POWER FLOWS AND MARGINS IN LINES UNDER RANK-1 CONTINGENCY OF IEEE-5 BUS SYSTEM

Line No	From bus	To bus	Line Flow (MVA)	Line Limit (MVA)	Margin Limit (MVA)
1	1	2	74.294	100	25.706
2	1	3	58.24	100	41.76
3	2	3	60.465	100	39.535
4	2	4	87.083	100	12.917
6	3	4	152.52	100	-52.525
7	4	5	147.22	100	-47.221

The further analysis is performed by varying GUPFC control parameters such as V_{se} from 0 p.u. to 0.05 p.u. in steps of 0.025 p.u. and voltage angle is varied from 0 deg to 360 deg in steps of 20 deg. The consolidated variation of voltage magnitudes at buses by varying the GUPFC control parameters is shown in Fig.7. From this figure, it is identified that, major variation is observed at bus-4 as at this bus GUPFC sending end is connected. Similarly, the next maximum variation is observed at bus-5, as this bus is connected nearer to device connected bus. The individual bus voltage magnitudes variation is shown in Fig.8. From this figure, it is observed that, voltage variation is increasing as V_{se} is increasing from 0 p.u. to 0.05 p.u. It is also observed that, minimum voltage magnitude is obtained when V_{se} is equal to 0.05 p.u. and θ_{se} is at 180 deg and maximum voltage magnitude is obtained when V_{se} is at 0.05 p.u. and θ_{se} is at 0 deg or 360 deg.

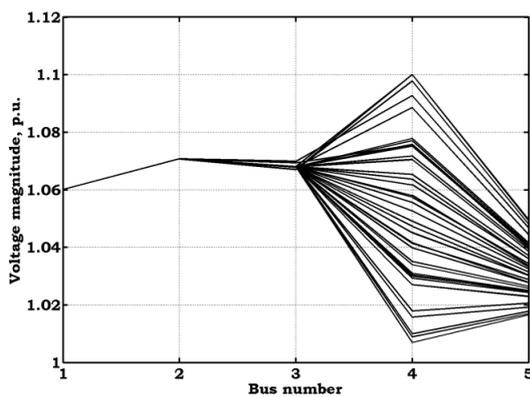


Fig.7. Consolidated variation of voltage magnitudes for IEEE-5 bus system

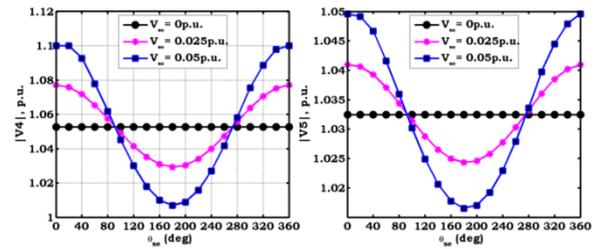


Fig.8. Individual variation of voltage magnitudes for IEEE-5 bus system

The consolidated variation of apparent power flow in lines by varying the GUPFC control parameters is shown in Fig.9. From this figure, it is identified that, due to variation of power flow in lines 4 and 6, major variation is observed in line 5. Similarly, the next maximum variation is observed in line 7, as this line is connected to device connected bus.

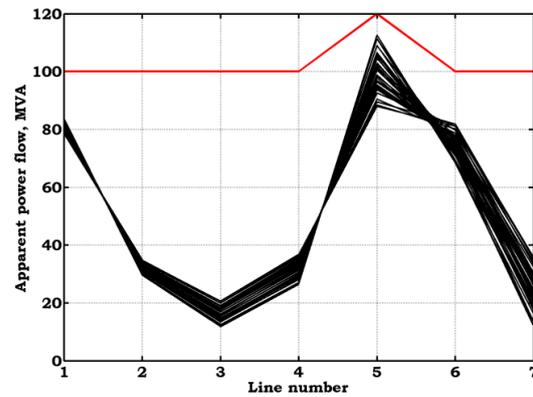


Fig.9. Consolidated variation of apparent power flows for IEEE-5 bus system

The variation of system active power losses by fixing V_{se} at constant value is shown in Fig.10. From this figure, it is observed that, active power loss variation is increasing as V_{se} is increasing from 0 p.u. to 0.05 p.u. It is also observed that, minimum losses are obtained when V_{se} is equal to 0.025 p.u. and θ_{se} is at 60 deg and maximum losses are obtained when V_{se} is at 0.05 p.u. and θ_{se} is at 240 deg.

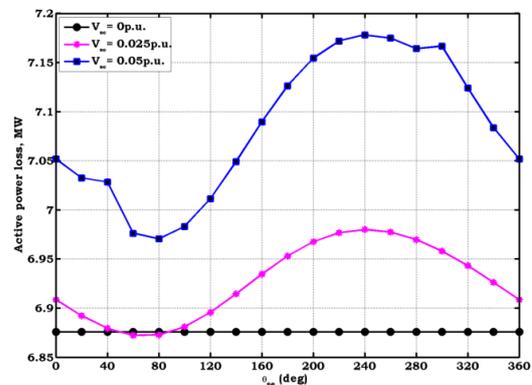


Fig.10. Variation of system active power losses when V_{se} is fixed for IEEE-5 bus system

The variation of system active power losses by fixing θ_{se} at constant value is shown in Fig.11. From this figure, similar type of inferences can be obtained as in Fig.10.

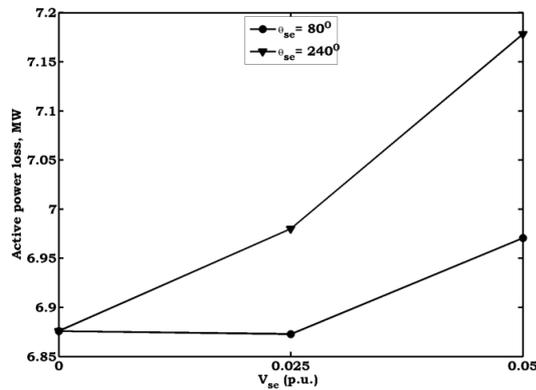


Fig.11. Variation of system active power losses when θ_{se} is fixed for IEEE-5 bus system

The variation of number of iterations and time taken to solve NR load flow with GUPFC is shown in Fig.12. From this figure, it is identified that, minimum number of iterations taken are 4 when V_{se} is at 0 p.u. and maximum iterations taken are 16 when V_{se} is at 0.05 p.u. Similarly, the time taken is increasing as V_{se} is increasing from 0 p.u. to 0.05 p.u. The maximum time taken is around 5 m.sec when V_{se} is at 0.05 p.u.

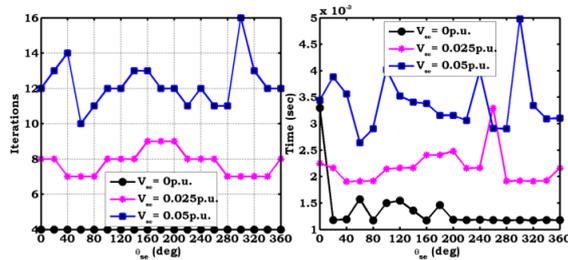


Fig.12. Variation of iterations and time taken for IEEE-5 bus system

B. Example-2

IEEE-14 bus system with twenty transmission lines is considered. Initially, contingency analysis is performed on this system and the obtained results are tabulated in Table.4. In this table, overloaded lines and their respective performance indexes for each of the contingency line are tabulated. The respective severity index values under each of the contingency are tabulated in Table.5. From this table, it is identified that, line connected between buses, 4 and 5 is the most critical one as it has highest severity index value when compared to other contingencies. The line flows under this critical contingency are tabulated in Table.6. From this table and the heuristic rules formulated in section.4, the optimal location to install GUPFC is identified between buses 4, 2 and 5 i.e. in lines 3 and 6. The further analysis is assumed that, IPFC is connected in this location.

TABLE.4. RESULT OF CONTINGENCY ANALYSIS OF IEEE-14 BUS SYSTEM

S. No.	Outage line	Over loaded lines	Line flow (MVA)	Line limit (MVA)	PI
1	1-5	1-2	241.111	150	1.607
		2-3	87.141	85	1.025
		4-7	31.79	30	1.06
		7-9	29.799	29	1.028
2	2-3	1-5	95.438	85	1.123
		2-4	93.614	85	1.101
		3-4	96.512	85	1.135
		5-6	47.851	45	1.063
3	2-4	1-5	92.291	85	1.086
		2-3	90.22	85	1.061
		5-6	47.769	45	1.062
4	2-5	1-5	91.529	85	1.077
		4-7	30.773	30	1.026
		7-9	29.536	29	1.019
5	3-4	1-2	163.933	150	1.093
		2-3	98.386	85	1.158
		5-6	45.423	45	1.009
		7-9	29.323	29	1.011
6	4-5	1-2	179.437	150	1.196
		2-3	89.145	85	1.049
		2-4	89.235	85	1.05
		5-6	62.118	45	1.38
		6-11	17.416	14	1.244
		6-13	23.768	22	1.08
		10-11	13.444	12	1.12
7	6-11	1-2	158.605	150	1.057
		4-7	31.819	30	1.061
		7-9	32.583	29	1.124
8	6-12	1-2	158.363	150	1.056
		5-6	45.631	45	1.014
		6-13	26.573	22	1.208
		7-9	29.305	29	1.011
9	6-13	1-2	159.057	150	1.06
		4-7	31.145	30	1.038
		7-9	31.958	29	1.102
		12-13	13.71	12	1.143
10	7-9	1-2	157.537	150	1.05
		5-6	60.712	45	1.349
		6-11	17.632	14	1.259
		6-13	24.157	22	1.098
11	9-10	10-11	13.088	12	1.091
		1-2	158.012	150	1.053
		5-6	49.24	45	1.094
12	9-14	6-11	15.191	14	1.085
		1-2	158.148	150	1.054
		5-6	51.102	45	1.136
		6-13	27.94	22	1.27
13	10-11	13-14	16.409	12	1.367
		1-2	158.364	150	1.056
		4-7	30.65	30	1.022
14	12-13	7-9	30.752	29	1.06
		1-2	158.176	150	1.055
		5-6	45.911	45	1.02
15	13-14	1-2	158.465	150	1.056
		4-7	30.98	30	1.033
		7-9	31.207	29	1.076

TABLE.5. SEVERITY INDEX VALUES OF IEEE-14 BUS SYSTEM

S.No.	Outage line	Severity Index	Rank
1	1-5	5.8135	4
2	2-3	4.8936	5
3	2-4	3.4324	11
4	2-5	3.2491	14
5	3-4	4.5755	8
6	4-5	9.5083	1
7	6-11	3.5054	9
8	6-12	4.6229	7
9	6-13	4.722	6
10	7-9	6.9047	2
11	9-10	3.4844	10
12	9-14	5.8839	3
13	10-11	3.2829	13
14	12-13	2.1529	15
15	13-14	3.3404	12

TABLE.6. POWER FLOWS AND MARGINS IN LINES UNDER RANK-1 CONTINGENCY OF IEEE-14 BUS SYSTEM

Line No	From bus	To bus	Line Flow (MVA)	Line Limit (MVA)	Margin Limit (MVA)
1	1	2	163.932	150	-13.9328
2	1	5	70.2651	85	14.7349
3	2	3	98.386	85	-13.386
4	2	4	44.7277	85	40.2723
5	2	5	33.1436	85	51.8564
7	4	5	50.5027	150	99.4973
8	4	7	29.7489	30	0.2511
9	4	9	16.3438	32	15.6562
10	5	6	45.4232	45	-0.4232
11	6	11	7.9251	14	6.0749
12	6	12	8.1479	32	23.8521
13	6	13	19.0136	22	2.9864
14	7	8	16.9261	32	15.0739
15	7	9	29.3233	29	-0.3233
16	9	10	6.8729	32	25.1271
17	9	14	10.2731	18	7.7269
18	10	11	3.8713	12	8.1287
19	12	13	1.7611	12	10.2389
20	13	14	5.7232	12	6.2768

To extend the effectiveness of the proposed GUPFC modeling, here five combinations of GUPFC control parameters are considered.

Case-1: $V_{seij}=0.02$; $Th_{seij}=72$; $V_{seik}=0.1$; $Th_{seik}=360$

Case-2: $V_{seij}=0.04$; $Th_{seij}=144$; $V_{seik}=0.08$; $Th_{seik}=288$

Case-3: $V_{seij}=0.06$; $Th_{seij}=216$; $V_{seik}=0.06$; $Th_{seik}=216$

Case-4: $V_{seij}=0.08$; $Th_{seij}=288$; $V_{seik}=0.04$; $Th_{seik}=144$

Case-5: $V_{seij}=0.1$; $Th_{seij}=360$; $V_{seik}=0.02$; $Th_{seik}=72$

The variation of bus voltage magnitudes for these five cases is shown in Fig.13. From this figure, it is observed that, bus-4 has major variation when compared to other buses, because GUPFC sending end is connected at this bus.

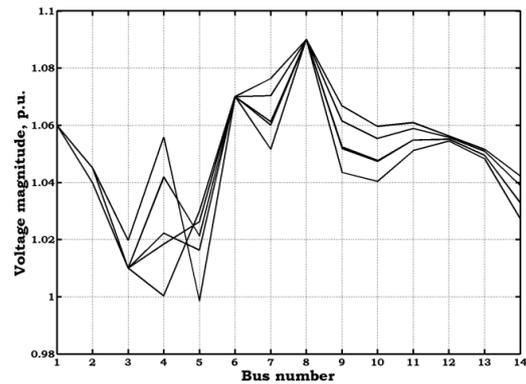


Fig.13. Variation of bus voltage magnitudes in five cases for IEEE-14 bus system

The variation of apparent power flow in transmission lines for these five cases is shown in Fig.14. Due to variation in device connected lines (3 and 6), maximum variation is observed in line 7, as it is connected to device connected buses. It is also observed that, because of this device, in most of the transmission lines, apparent power is flowing nearer to its thermal limit.

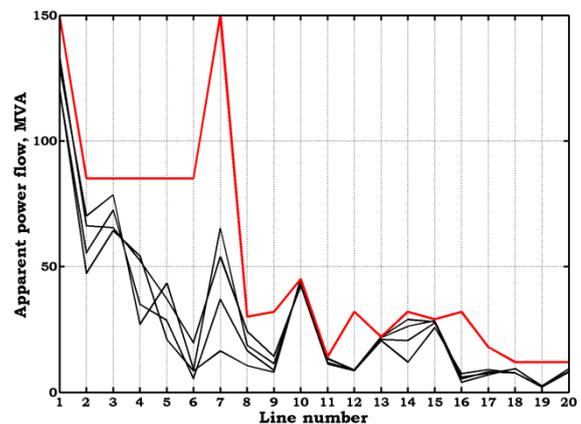


Fig.14. Variation of line apparent power flows in five cases for IEEE-14 bus system

The variation of active power losses for the five cases is shown in Fig.15. From this figure, it is observed that, minimum losses are obtained in case-2 and maximum losses are obtained in case-5.

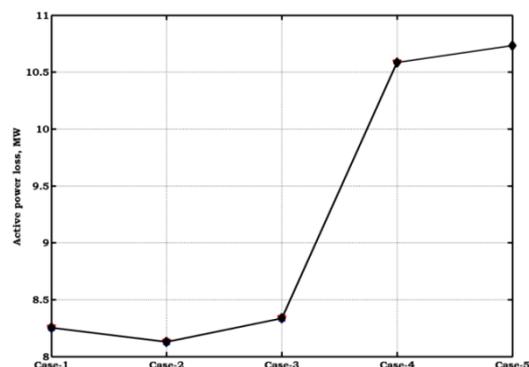


Fig.15. Variation of system active power losses in five cases for IEEE-14 bus system

VI. CONCLUSION

In this paper, voltage source based power injection model of GUPFC has been presented. Using this, the effect of this device is analyzed on system parameters. An optimal location strategy based on contingency analysis through performance and severity indexes has been presented. The system control parameters such as voltage magnitudes at buses, apparent power flows in transmission lines, and system active power losses has been analyzed by varying the device control parameters. The proposed methodology has been tested on standard IEEE-5 bus and IEEE-14 bus test systems has been analyzed.

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