

SIMULATION MODELLING ON AN **INTEGRATED NON-ISOLATED** BUCK-FLYBACK AC-DC CONVERTER FOR POWER QUALITY IMPROVEMENT

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Abstract: In this proposed new converter is an inherent integration of a buck converter and a flyback converter, which operates in either fly back mode or buck mode according to whether the input voltage is lower or higher than the output voltage. In this way, the dead zones of ac input current in traditional buck PFC converter are eliminated. Therefore, the proposed integrated buck-fly back non- isolated PFC converter can achieve high PF under universal ac input range.A proposed converter will be simulated in MATLAB/SIMULINK environment.A 100-W prototype was built up to verify the theoretical analysis of the proposed integrated buck-flyback non-isolated PFC converter. Objective of this proposed topology is modeling of High power factor correction converter by integration of a buck-Fly back input current shaper with a Auxiliary fly-back converter.proposed converter operates in fly back mode when the input voltage is lower than the output voltage and operates in buck mode when the input voltage is higher than the output voltage.

Keywords: AC-DC, buck-flyback converter, harmonics currents, high power factor(PF).

1. INTRODUCTION

1.1GENERAL

reduce the harmonic current to meet the IEC61000-3-2 limits. Some special power products such as lighting buck PFC converter can achieve a relatively high equipments should meet the stricter IEC61000-3-2 class C limits. Power factor correction (PFC) is a good method for average input current and rms current, while the voltage providing an almost sinusoidal input current. The boost stress of the switch is also low. Therefore, the buck PFC converter is the most popular topology for PFC applications due to its inherent current shaping ability. However, with universal input, usually a 400 Vdc output voltage is required for the boost PFC. The boost PFC cannot achieve high efficiency at low line input because it works with large duty cycle in order to get high-voltage conversion gain. Therefore, it is hard to increase the power density of boost PFC converter due to the thermal concern buck PFC converter. at low line input.

well applied to the ac/dc converters because it canprovide almost sinusoidal input current. In this way, the ac/dc power converters can meet the IEC61000-3-2 limits. For some special industrial products such as lighting equipment, the PFC converter can also help meet the stricter IEC61000-3-2 Class C limits. In the past few years, the boost PFC converter was the mostpopular topology due to its inherent shaping ability of the input current. However, the boost PFC cannot achieve high efficiency at low line because it works with large duty cycle in order to get high voltage conversion gain. Some other topologies such as

the SEPIC converter can achieve high PF and reduce the Nowaday's most ac/dc power converters are forced to output voltage stress. However, the high voltage stress of switch reduces the efficiency and increases the cost. The efficiency particularly at low input voltage due to the low converter hasdrawn much attention. However, it is difficult for the buck PFC converter to pass the IEC61000-3-2 Class C limits due to the dead zones in the input current which occur when the input voltage is lower than output voltage Vo. An improved constant on-time (COT) control for buck PFC converter is introduced in this improved COT control can help improve the PF of the

The power factor (PF) correction (PFC) technique is However, this improved control method needs carefully designed parameters and is still not easy to meet the limits imposed by IEC61000-3-2Class C limits at the low line input voltage. Another way to improve the PF of the buck PFC converter isto modify the structure of the conventional buck converter. According to this idea, the integrated quadratic buck-boost-buck converter was proposed in this proposed topology integrates a buckboost input current shaper with a quadratic buck converter to eliminate the dead zones of the input current and then achieve high PF. However, the complex structure of this topology makes it unsuitable for actual applications. The buck converter can also be integrated with a flyback



converter. Two combined buck-flyback converters were The block diagram of an integrated non-isolated buckintroducedin, which the dead zones of the input current flyback converter consists of six blocks. They are known can be eliminated with the auxiliary flyback converter. as source, rectifier, buck-flyback converter, PWM However, an additional diode leading to additional losses switching controller, driver circuit, regulated power is inserted in the power loop when these two topologies supply. operate in buck mode.

The structure of the proposed converter is very simple. It is formed by adding two rectifier diodes, one winding of is an AC source. The rating of source is 230v/30v/40v, the inductor, and one switch into the conventional buck PFC converter. The source nodes of the added switch Q2 and the buck switch Q1 are connected to the ground. Therefore, these two switches can beeasily driven without floating drivers. There are two different operation modes in a line period for the proposed converter. The proposed converter operates in flyback mode when the input voltage is lower than the output voltage and operates in buck mode when the input voltage is higher than the output voltage. In this way, there are no dead zones in the input current of the proposed converter[1]-[22]. Therefore, it can achieve DRIVE CIRCUIT high PF and pass the IEC61000-3-2 Class C limits easily. Moreover, the power loops of the buck mode and flyback mode are separated, and no additional component causing losses is added to the power loops. Obviously, the proposed integrated buck-fly back converter can achieve higher efficiency than the combined buck-fly back converters introduced in detailed operation principle and circuit parameter design considerations will be presented.

2. SYSTEM ANALYSIS

2.1PRINCIPLES **OPERATIONS** OF INTEGRATED BUCK-FLYBACK

The integrated buck-fly back non isolated PFC 3.1 GENERAL converter is proposed. The proposed converter operates in Simulation has become a very powerful tool for industrial flyback mode when the input voltage is lower than the application as well as in academics, nowadays. It is now output voltage and operates in buck mode when the input essential for an electrical engineer to understand the voltage is higher than the output voltage. Buck and Fly- concept of simulation to study the system or circuit back mode operation is controlled by control signal Vph. behavior without damaging it .The tools for doing the Control signal Vph is the result of the magnitude simulation in various fields are available in the market for comparison between Vin and Vboundry. The driving engineering professionals. Many industries are spending a signals VG1 and VG2 are controlled by Vph for the considerable amount of time and money in doing different operation modes alternately. the proposed integrated buck-flyback non-isolated PFC converter the research and development (R&D) work, the simulation operates in buck mode when Vph is in high logic level, plays a very important role. Without simulation it is quiet while it operates in flyback mode when Vph is in low logic level. Transition processes between those two modes are natural.



Fig. 2.1 Functional block Diagram

SOURCE

The source used for the buck-flyback converter 3Amps.

AC-DC RECTIFIER

Ac-dc rectifier converts ac voltage to dc voltage for the buck and boost operation. The diodes used in the rectifier operate alternatively. They are named as D1, D2, D3, and D4.At a time any two diodes conducting.

REGULATED POWER SUPPLY

This regulated power supply provides supply for both PWM switching controller and driver circuit.

This driving circuit gives the driving signals to drive the PWM switching controller for the pulse width modulation generation.

PWM SWITCHING CONTROLLER

This controller compares sine wave and carrier wave and generates pulse width modulation for the control signals. This pulse width modulation compared with the boundary voltage and two control pulses are generated. These two pulses used to control the diode conduction. First pulse is used for positive half cycle and second pulse is used for next half cycle.

3. SOFTWARE ANALYSIS

simulation before manufacturing their product. In most of impossible to proceed further.

3.2 THE ROLE OF SIMULATION

Electrical power systems are combinations of electrical circuits and electro mechanical devices like motors and generators. Engineers working in this discipline are constantly improving the performance of the systems. Requirements for drastically increased efficiency have forced power system designers to use power electronic devices and sophisticated control system concepts that tax traditional analysis tools and techniques. Further complicating the analyst's role is the fact that the system is often so nonlinear that the only way to understand it is through simulation.Land-based power generation from hydroelectric.



3.3 SIM POWER SYSTEMS

SimPower Systems is a modern design tool that allows because all the electrical parts of the simulation interact scientists and engineers to rapidly and easily build models that simulate power systems. Sim Power Systems uses the simulink environment, allowing you to build a model designers can also use MATLAB toolboxes and Simulink using simple click and drag procedures. Not only can you block sets. Sim Power Systems and Sim Mechanics share draw the circuit topology rapidly, but your analysis of the a special Physical Modeling block and connection line circuit can include its interactions with mechanical, interface.

thermal, control, and other disciplines. This is possible with the extensive Simulink modeling library. Since Simulink uses MATLAB as its computational engine,

4. SIMULATION



Fig .4.1Simulation circuit



10.					Battery voltage				
*******	~~~~~	~~~~~~	~~~~~	******	******	******	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	******	~~~~~
20									
×									
10									
20									
0	0.2	0.4	0.6	0.8	1	1.2	1.4	1.6	1.8

Fig.4.2 Battery voltage waveform



Fig.4.3 Inverter output voltage and current waveform



Fig.4.4 Source power factor waveform



Fig.4.5 Inverter switching pulse waveform (S1-S4)



6. CONCLUSION

Simulation Modelling on An Integrated Non-Isolated Buck-Flyback AC-DC Converter For POWER QUALITY Improvement is investigated.

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BIOGRAPHIES



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