

Voltage stability and Power flow improvement using STATCOM and TCSC

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Abstract: FACTS controllers are increasingly used to improve transmission capability of transmission lines with galloping energy consumption; the demand of transmission line is increasing. It is imperative to use existing transmission system to its full capacity. FACTS controllers play an important role in enhancement in power flow capacity and improvement of voltage stability. This paper investigates the application of STATCOM and TCSC for Voltage stability & power flow enhancement. The case has been tested on IEEE-14 bus system.

Keywords: Power flow enhancement, Voltage stability improvement, STATCOM, TCSC.

I. INTRODUCTION

With improvement in economic development of a country, the per capita energy consumption increases. Electric energy being a most common form of energy being used translates into overall higher energy demand on the power network. This galloping energy demand has not kept pace with development of transmission sector. It's development is further affected by environmental restrictions, right-of-way issues, economic consideration etc.

Hence, constructing a new transmission line more expensive than utilizing existing transmission line optimally. Generally, all transmission line operates for below thermal limit and hence there is simple scope for the line to carry more power. This is facilitated by a class of power electronic device called FACTS or Flexible AC transmission system. This paper studies the effect of using two such FACTS device viz. STATCOM (static synchronous compensator) and TCSC (Thyristor controlled series capacitor) for Voltage stability & Power Flow Enhancement.

In the following sections, section-2 discusses literature review, section-3 gives mathematical modeling of FACTS devices used and section-4 gives simulation results. The conclusion is given in section-5.

II. LITERATURE REVIEW

Hingorani & Gyugi^[1] had proposed the concept of FACTS devices in early eighties. They had shown the improvement of power system performance by using power electronic devices called FACTS devices. SVC and TCSC were first generation FACTS devices using thyristors while STATCOM, UPFC etc. are second generation FACTS devices using GTO, IGBT, IGCT etc. Singh and Srivastava^[2] had demonstrated improvement in load ability of power system using FACTS devices. They had demonstrated the proposal of IEEE-14 and IEEE-30 bus system. Kessel and Glavitsch^[3] had estimated voltage stability and line load ability of FACTS devices. They showed that FACTS devices could improve line load ability as well as stability of the system.

Anwar and Tanmoy^[4] had used STATCOM and SVC for improvement of voltage stability. They concluded that STATCOM was better than SVC in reactive power injection. His proposal was demonstrated on IEEE-14 bus system.

Sharvana and Gholamreza^[5] compared the performance of STATCOM and SVC for voltage stability improvement. They concluded that during contingency situation when bus voltage dips than STATCOM can still provide reactive power support but reactive power output of SVC reduces. Siddiqui and Deb^[6] had used SVC and STATCOM among other fact devices to improve load ability of transmission lines there by reducing congestion. They had demonstrated the voltage stability improvement by STATCOM and SVC on IEEE-14 bus system.

N. Taleb et al^[7] had studied voltage collapse phenomenon using SVC and STATCOM. They found that reactive power output of SVC reduces with reduction in bus voltage at the line contingency. Hence STATCOM was better suited for voltage stability improvement.

III. MODELING OF FACTS DEVICES

3.1 Modeling of STATCOM

STATCOM is a shunt connected reactive power compensator whose inductive and capacitive output current can be controlled independent of system AC voltage. It generates or absorbs independently controllable real and reactive power at its output terminal when fed from a energy storage device at the input.

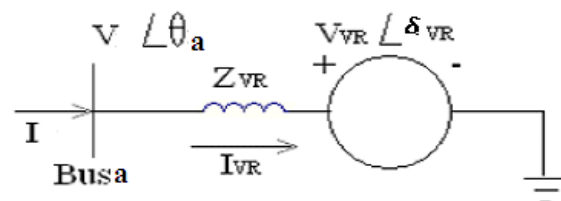


Fig 3.1 STATCOM equivalent circuit

Assuming following voltage source representation—

$$E_{VR} = V_{VR}(\cos \delta_{VR} + j \sin \delta_{VR}) \dots\dots\dots (1)$$

Also, $S_{VR} = V_{VR} I_{VR}^* = V_{VR} Y_{VR}^* (V_{VR}^* - V_a^*) \dots\dots (2)$ following active and reactive power equations can be obtained after some complex operation.

$$P_{VR} = V_{VR}^2 G_{VR} + V_{VR} V_a [G_{VR} \cos(\delta_{VR} - \theta_a) + B_{VR} \sin(\delta_{VR} - \theta_a)] \quad (3)$$

$$Q_{VR} = -V_{VR}^2 B_{VR} + V_{VR} V_a [G_{VR} \sin(\delta_{VR} - \theta_a) - B_{VR} \cos(\delta_{VR} - \theta_a)] \dots\dots (4)$$

$$P_a = V_a^2 G_{VR} + V_a V_{VR} [G_{VR} \cos(\theta_a - \delta_{VR}) + B_{VR} \sin(\theta_a - \delta_{VR})] \dots\dots (5)$$

$$Q_a = -V_a^2 B_{VR} + V_a V_{VR} [G_{VR} \sin(\theta_a - \delta_{VR}) - B_{VR} \cos(\theta_a - \delta_{VR})] \dots\dots (6)$$

Linearized model is given by following equations using above equations –

$$\begin{bmatrix} \Delta P_a \\ \Delta Q_a \\ \Delta P_{vr} \\ \Delta Q_{vr} \end{bmatrix} = \begin{bmatrix} \frac{\partial P_a}{\partial \theta_a} & \frac{\partial P_a}{\partial V_a} & \frac{\partial P_a}{\partial \delta_{vr}} & \frac{\partial P_a}{\partial V_{vr}} \\ \frac{\partial Q_a}{\partial \theta_a} & \frac{\partial Q_a}{\partial V_a} & \frac{\partial Q_a}{\partial \delta_{vr}} & \frac{\partial Q_a}{\partial V_{vr}} \\ \frac{\partial P_{vr}}{\partial \theta_a} & \frac{\partial P_{vr}}{\partial V_a} & \frac{\partial P_{vr}}{\partial \delta_{vr}} & \frac{\partial P_{vr}}{\partial V_{vr}} \\ \frac{\partial Q_{vr}}{\partial \theta_a} & \frac{\partial Q_{vr}}{\partial V_a} & \frac{\partial Q_{vr}}{\partial \delta_{vr}} & \frac{\partial Q_{vr}}{\partial V_{vr}} \end{bmatrix} \begin{bmatrix} \Delta \theta_a \\ \Delta V_a \\ \Delta \delta_{vr} \\ \Delta V_{vr} \end{bmatrix} \dots\dots (7)$$

3.2 Modelling of TCSC

TCSC can be considered as a variable series reactance whose magnitude can be adjusted to control the power flow in a branch. The amount of reactance X_{TCSC} can be found by Newton's method.

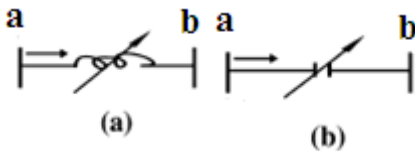


Fig 3.2 TCSC equivalent circuit

Fig 3.2 TCSC equivalent circuit in inductive and capacitive region. Inductive susceptance is given by

$$B_{aa} = B_{bb} = \frac{-1}{X_{TCSC}} \quad (8)$$

$$B_{ab} = B_{ba} = \frac{1}{X_{TCSC}} \quad (9)$$

For capacitive susceptance, signs are reversed. Active and reactive power equations at bus a are given by-

$$P_a = V_a V_b B_{ab} \sin(\theta_a - \theta_b) \quad (10)$$

$$Q_a = -V_a^2 B_{aa} - V_a V_b B_{ab} \cos(\theta_a - \theta_b) \quad (11)$$

Linearizing above equation for active power P_{ab}^{reg} flowing from bus a to bus b-

$$\begin{bmatrix} \Delta P_a \\ \Delta P_b \\ \Delta Q_a \\ \Delta Q_b \end{bmatrix} = \begin{bmatrix} \frac{\partial P_a}{\partial \theta_a} & \frac{\partial P_a}{\partial \theta_b} & \frac{\partial P_a}{\partial V_a} & \frac{\partial P_a}{\partial V_b} & \frac{\partial P_a}{\partial X_{TCSC}} \\ \frac{\partial P_b}{\partial \theta_a} & \frac{\partial P_b}{\partial \theta_b} & \frac{\partial P_b}{\partial V_a} & \frac{\partial P_b}{\partial V_b} & \frac{\partial P_b}{\partial X_{TCSC}} \\ \frac{\partial Q_a}{\partial \theta_a} & \frac{\partial Q_a}{\partial \theta_b} & \frac{\partial Q_a}{\partial V_a} & \frac{\partial Q_a}{\partial V_b} & \frac{\partial Q_a}{\partial X_{TCSC}} \\ \frac{\partial Q_b}{\partial \theta_a} & \frac{\partial Q_b}{\partial \theta_b} & \frac{\partial Q_b}{\partial V_a} & \frac{\partial Q_b}{\partial V_b} & \frac{\partial Q_b}{\partial X_{TCSC}} \end{bmatrix} \begin{bmatrix} \Delta \theta_a \\ \Delta \theta_b \\ \Delta V_a \\ \Delta V_b \\ \Delta X_{TCSC} \end{bmatrix} \dots\dots (12)$$

ΔP_{ab}^{XTCSC} is given by

$$\Delta P_{ab}^{XTCSC} = P_{ab}^{reg} - P_{ab}^{XTCSC.cal} \quad (13)$$

This is active power mismatch for series reactance. Also,

$$\Delta X_{TCSC} = X_{TCSC}^i - X_{TCSC}^{i-1} \quad (14)$$

The state variable X_{TCSC} is updated at the end of each iterative step

$$X_{TCSC}^i = X_{TCSC}^{i-1} + \left[\frac{\Delta X_{TCSC}}{X_{TCSC}} \right]^i X_{TCSC}^{i-1} \quad (15)$$

IV. RESULT AND DISCUSSIONS

Newton raphson load flow carried out on IEEE-14 bus system. STATCOM controls the bus voltage to the specified value, in table -1 the base case voltage in bus 14 is 0.9417 which is lowest value, after connecting STATCOM to that bus the bus voltage improves to 1.0 having reactive power supplied by STATCOM is -0.2445 at source voltage magnitude and phase angle is 1.024 and -0.3175 respectively. By increasing the load by 20%, the reactive power and voltage (both magnitude and phase angle) is -0.3053 and 1.029, -0.3883 respectively to make the bus voltage magnitude to 1.0. By decreasing the load by 20%, the reactive power and voltage (both magnitude and phase angle) is -0.1887 and 1.0185, -0.2485 respectively to make the bus voltage magnitude to 1.0. From this discussion the STATCOM voltage magnitude is more than the bus voltage so it works on the capacitive mode and supplies reactive power to the system. About other bus, the data is given in table-1.

In table -2 the lowest base case active power (pu) is 0.0944 the branch 9-14 by connecting TCSC in this branch the active power improved to 0.12 and reactance value is -0.2771. Then increasing 20% load, the reactance value is -0.1071 to make the active power 0.12. Then decreasing 20% load the maximum active power can be improved is 0.099 at this reactance limit, the reactance value is -0.2956. In all the cases TCSC operates in capacitive mode. For the test of TCSC in inductive mode, the active power in branch 2-3 is decreased from 0.7443 (base case value) to 0.6, at that time TCSC reactance is 0.1195, the reactance value shows that TCSC works in inductive mode. Like this for other branch the data is given in table-2.

V. CONCLUSION

STATCOM and TCSC were implemented in IEEE-14 bus system using Newton-Raphson load flow algorithm.

By using the STATCOM model, the voltage magnitude at the bus is improved on base case load, 20% increasing load and 20% decreasing load.

By using TCSC, the active power flow is improved in the branch on base case load, 20% increasing load and 20% decreasing load.

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APPENDIX-I

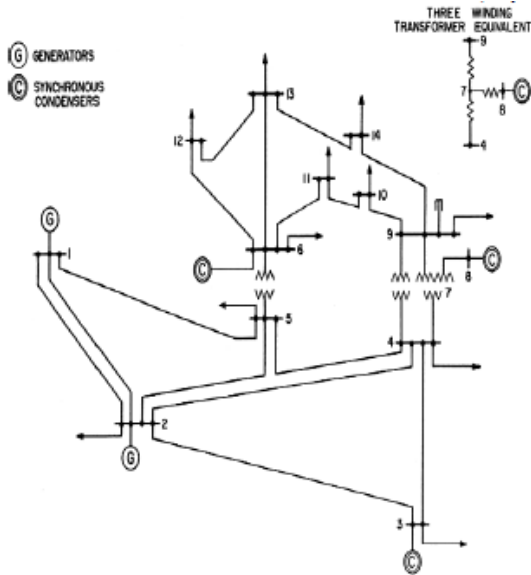


Figure-1 IEEE -14 bus system

TABLE-1

Bus No	Base Case voltage (pu)	With STATCOM (on base case load)			20% increased load (With STATCOM)			20% decreased load (With STATCOM)		
		Reactive power (pu)	Source Voltage magnitude & angle (pu)	Reactive power (pu)	Source Voltage magnitude & angle (pu)	Reactive power (pu)	Source Voltage magnitude & angle (pu)			
8	0.989		1.0318 -		1.0475 -		1.0174 -			
8	0.997		0.1830		0.2254		0.1416			
4	0.978		1.0123 -		1.0267 -		0.9993 -			
4	0	1.0	0.1548	1.0	0.1911	1.0	0.1192			
5	0.959	1.0	1.0262 -	1.0	1.0342 -	1.0	1.0187 -			
5	1.0	-0.3276	0.2416	1.0	-0.4980	1.0	-0.1772			
7	1.0	-0.1241	0.2746	1.0	-0.2746	1.0	0.0865			
9	1.0	-0.2684	1.0338 -	1.0	-0.3534	1.0	-0.1905			
10	1.0	-0.2497	0.2759	1.0	-0.4447	1.0	-0.2608			
11	1.0	-0.2747	1.0268 -	1.0	-0.3461	1.0	-0.2074			
12	1.0	-0.1762	0.2860	1.0	-0.2210	1.0	-0.1339			
13	1.0	-0.1238	1.0173 -	1.0	-0.1513	1.0	-0.0971			
14	1.0	-0.2768	0.2836	1.0	-0.3405	1.0	-0.2136			
3	0.970	1.0	1.0122 -	1.0	1.0149 -	1.0	1.0096 -			
3	0.964	1.0	0.2954	1.0	0.3616	1.0	0.2310			
2	0.941	1.0	1.0270 -	1.0	1.0330 -	1.0	1.0211 -			
7	0.941	1.0	0.2971	1.0	0.3636	1.0	0.2324			
7	0.941	1.0	1.0240 -	1.0	1.0297 -	1.0	1.0185 -			
7	0.941	1.0	0.3175	1.0	0.3883	1.0	0.2485			

TABLE-2

Branch (From- To)	Base Case active power (pu)	With TCSC (on base case load)		20% increased load (With TCSC)		20% decreased load (With TCSC)	
		Active power (pu)	TCSC Reactance (pu)	Active power (pu)	TCSC Reactance (pu)	Active power (pu)	TCSC Reactance (pu)
4-9	0.1608	0.25	-0.2771	0.25	-0.1847	0.20	-0.2741
5-6	0.4403	0.55	-0.1552	0.55	-0.0121	0.55	-0.2937
6-13	0.1777	0.25	-0.1614	0.25	-0.0861	0.25	-0.2425
7-9	0.2829	0.45	-0.2213	0.45	-0.1511	0.45	-0.2909
9-14	0.0944	0.12	-0.2771	0.12	-0.1071	0.099	-0.2956
2-3	0.7433	0.6	0.1195	-	-	-	-